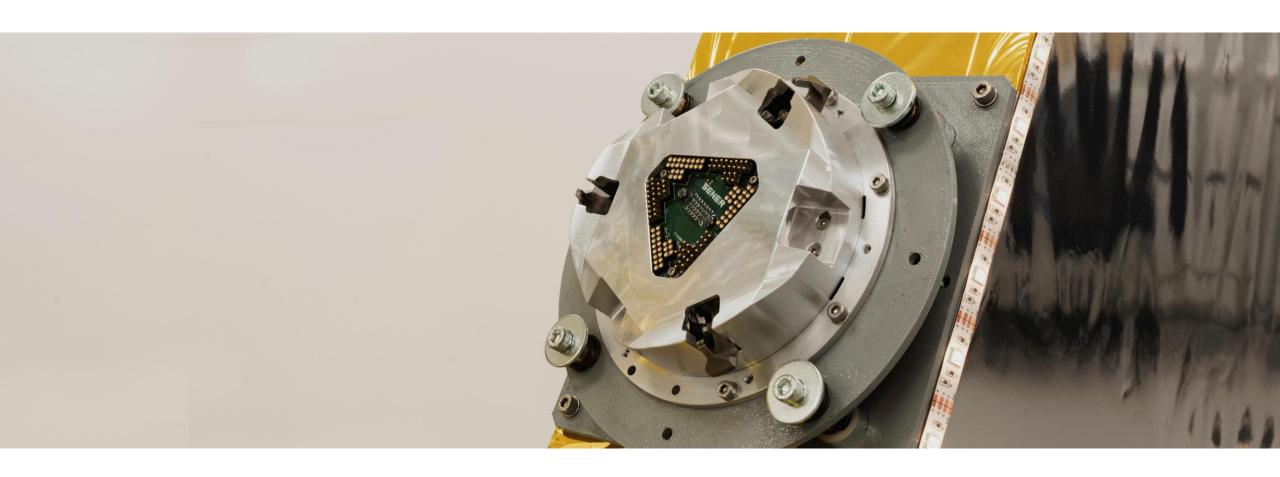
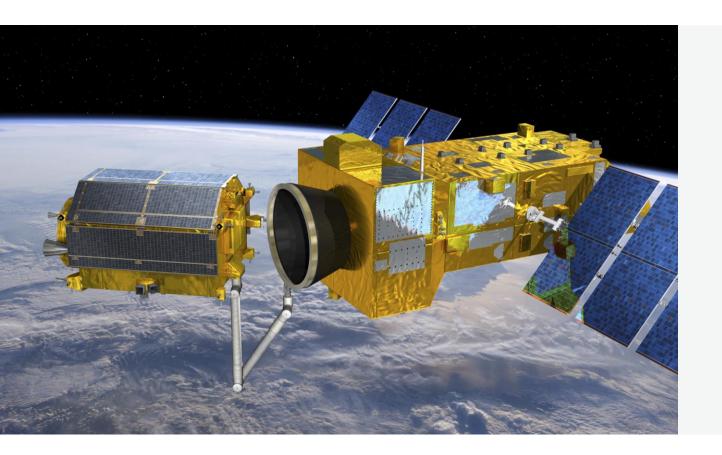
©⊕ sener



SIROM Roadmap for future In-Orbit Servicing Applications ASTRA | 18-20 October 2023 | Leiden (The Netherlands)

Context In-Orbit Servicing and Assembly



<u>Space robotics</u> is one of the key technologies for future European space missions

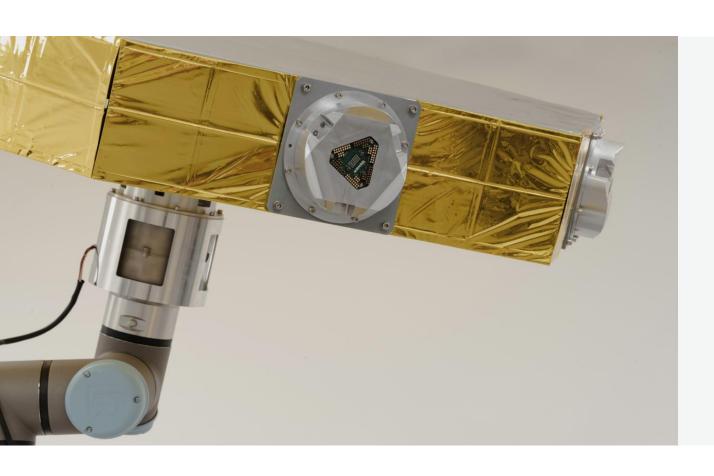
- In-Orbit Servicing (IOS)
- In-Space Manufacturing & Assembly (ISMA)

<u>Modular designs</u>: exchangable modules, costeffective



Standard Interfaces to connect modules

Context SIROM development



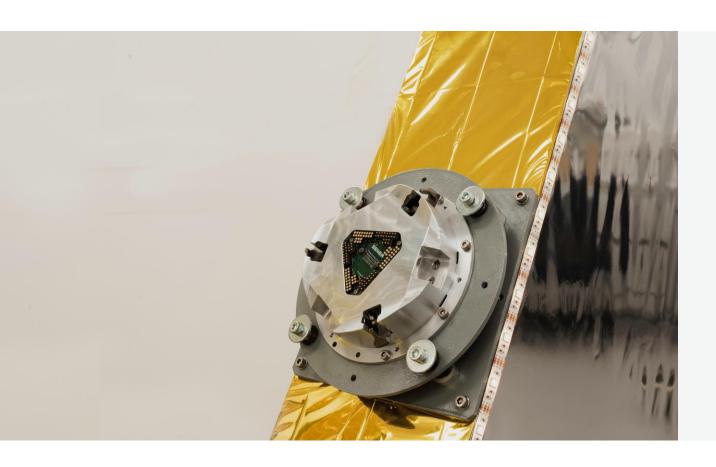
SIROM developed in the frame of EU's H2020 (OG5) for space robotics missions.

Involvement in European projects:

- EROSS (led by Thales Alenia)
- PERIOD (led by Airbus)
- MIRROR (led by GMV)

Feedback from stakeholders for improvements in the design → New SIROM family of products

ContextContent



- » SIROM Design Upgrades
- Mechanism upgrades
- Electronics upgrades
- » Family-oriented product
- Family E
- Family F
- Family G
- » Flight adaptation
- » Refuelling IF validation
- » On-going projects & timeline

SIROM Design New families

Redesign of SIROM into 3 families:

- Family E: data & power transfer
- Family F: fluidic transfer
- Family G: fluid, data, and power transfer

Aspects for improvement:

- Family-oriented design → Less cost, lead time
- Refuelling interface → New applications
- Design for flight → IOD foreseen for 2026

SIROM E (Passive)

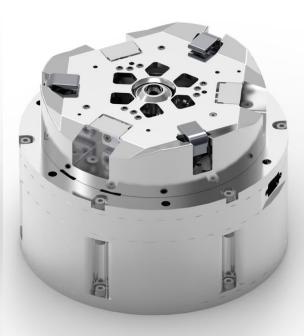


SIROM G (Passive)









SIROM G (Active)

SIROM Design Mechanism upgrades

Mechanism

- ESD Cover to protect the POGO pins
- Second actuator (BLDC) to pull the cover
- Pushing rod in SIROM E to pull passive covers
- Fluid connector deployment in SIROM F/G
- Latches upgrade to allow higher forces

Sensors

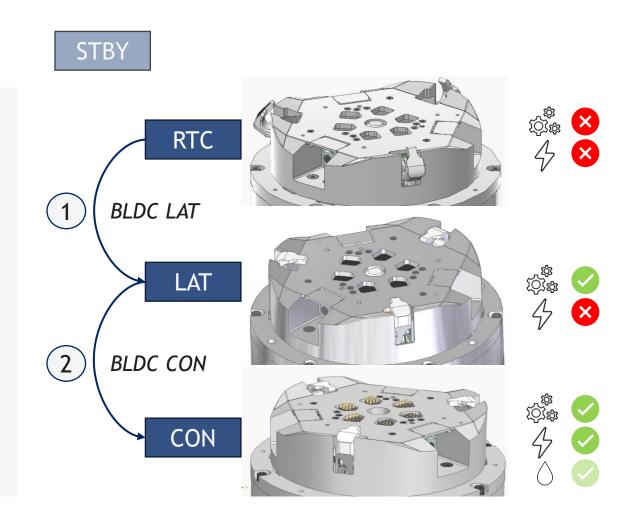
- Redundancy for position hall sensors
- Proximity sensors as navigation aid



SIROM Design Electronics upgrades

- New state diagram for SIROM operation, common for all families
- Modified circuits for additional motor driver and sensors
- Single PCA for reduced volume
- Integrated or external unit for SIROM E
- New power block to add configurable power supply rails
- More powerful microcontroller

Breadboard model of electronics already tested at functional block level



SIROM Design Family oriented product

Manufacturing process → High lead times and costs → New families with shared elements to minimize problem

- SIROM E: "evolution" of SIROM C
- SIROM F: concept for refuelling
- SIROM G: SIROM E+F

Fluid connector forces external electronics unit.

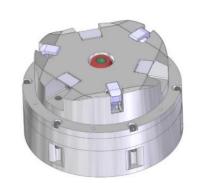
SIROM B Obsolete



SIROM C Ground demos



SIROM F Fluidic







SIROM G Electrical/fluidic



Electrical

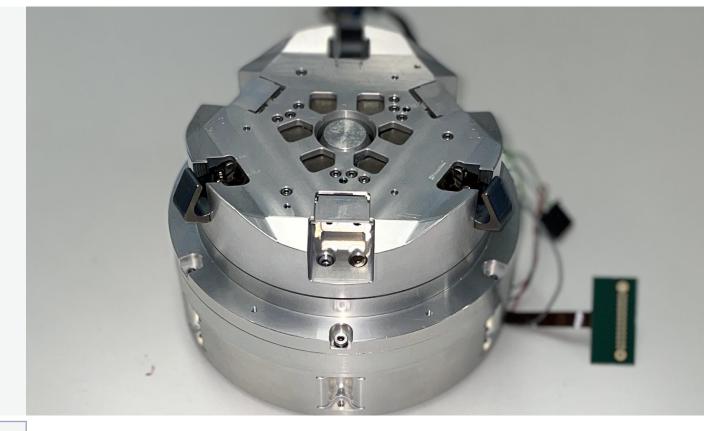
SIROM Design Refuelling validation

Design & Prototype

- Fluid connector from SENER's RIDER
- Prototype for SIROM E with pushing rod
- Assembly in 2023 → Decision to split operation in two stages

Remaining tests for 2023

- Seal selection and leakage tests
- Misalignment test
- SIROM G included in EROSS IOD



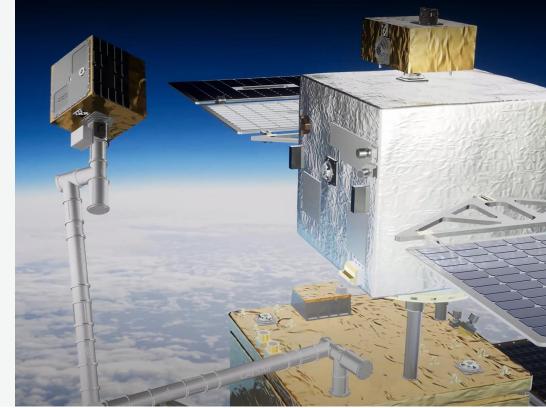


Development of a robotic Fluid Transfer interface based on RIDER connector (Gonzalo Guerra, ASTRA 2022)

SIROM Design Flight adaptation

Main objective: prepare design for flight applications

- ESD cover for protection
- Flight actuator (New space)
- Rad-tol EEE selection (New space)
- External electronics (Cubesat)
- Docking simulations for free-flying capture



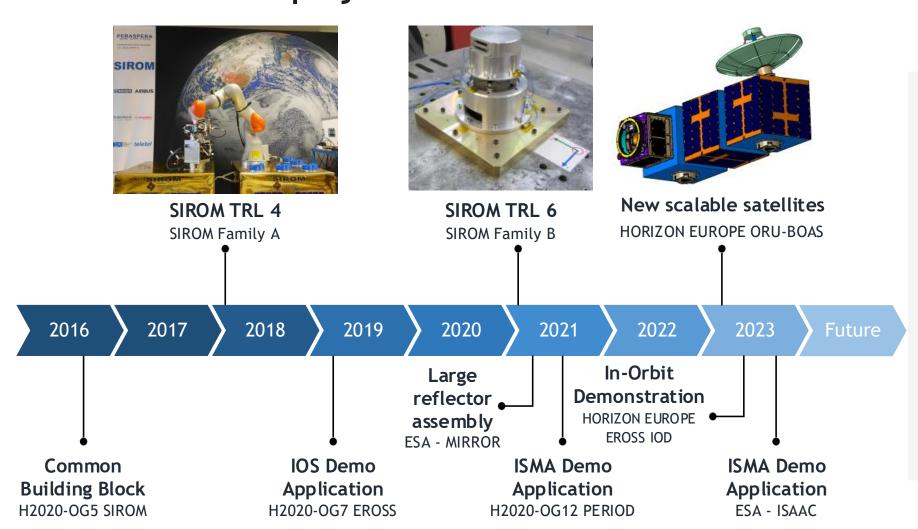
Courtesy of Thales Alenia Space



Mathematic modelling, simulation, test and correlation of a capture before contact docking mechanism (Alejandro Lázaro, ESMATS 2023)

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SIROM Roadmap Past & future projects



EROSS IOD

Orbital RDV and servicing (IOD foreseen in 2026)

ORU-BOAS

Development by SENER for modular satellites

ISAAC

www.group.sener

Demonstration of ISMA of large structures

Conclusions



In the past two years, several improvements have been made towards future in-orbit applications

SIROM is present in different European IOS and ISMA projects that will help to gain valuable insight from stakeholders

Standard Interfaces is a necessary building blok for the future of space robotics



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